

# Inf2320 Chapter 6

17th November 2003

## Exercises

### 6.1+6.2

*Algorithm for solving quadratic equations, with input data checks.*

```
Quadratic ( $a, b, c$ )
  if  $a = 0$  and  $b = 0$  and  $c \neq 0$ 
    write error message
  else if  $a = 0$ 
    return  $-c/b$ 
  else
     $r_1 = (-b + \text{sqrt}(b^2 - 4ac))/(2a)$ 
     $r_2 = (-b - \text{sqrt}(b^2 - 4ac))/(2a)$ 
    if  $r_1 = r_2$ 
      return  $r_1$ 
    else
      return  $r_1, r_2$ 
    end if
  end if
```

### 6.3

*Algorithm for solving quadratic equations, not using imaginary numbers.*

```
Quadratic ( $a, b, c$ )
  if  $a = 0$  and  $b = 0$  and  $c \neq 0$ 
    write error message
  else if  $a = 0$ 
    return  $-c/b, 0$ 
  else if  $b^2 \geq 4ac$ 
     $r_1 = (-b + \text{sqrt}(b^2 - 4ac))/(2a), 0$ 
     $r_2 = (-b - \text{sqrt}(b^2 - 4ac))/(2a), 0$ 
    if  $r_1 = r_2$ 
      return  $r_1$ 
    else
      return  $r_1, r_2$ 
  else
     $r_1 = -b/(2a), \text{sqrt}(4ac - b^2)$ 
     $r_2 = -b/(2a), -\text{sqrt}(4ac - b^2)$ 
    if  $r_1 = r_2$ 
      return  $r_1$ 
    else
      return  $r_1, r_2$ 
  end if
```

### 6.5

Use the following pseudocode:

```
 $\Delta t = T/N$ 
 $u_0 = U_0$ 
write  $(0, u_0)$  to file
for  $i = 1, \dots, N$ 
   $u_i = \text{heun}(f, u_{i-1}, \Delta t, 1)$ 
  write  $(i\Delta t, u_i)$  to file
end for
```

The number of  $f$ -function evaluations is now  $3N$  instead of  $3 \sum_{i=1}^N i$ .

## 6.6

*Generalized Heun's method.*

```
heun(f, U0, Δt, N)
  u = U0
  for n = 0, ..., N - 1
    u ← u +  $\frac{\Delta t}{2}$  [f(u, nΔt) + f(u + Δt f(u, nΔt), (n + 1)Δt)]
  end for
  return u
```

## Projects

### 6.7.1; Computing the volume of a Cylindrical Container

a)

$$\begin{aligned} V &= \int_0^H \int_0^{2\pi} \int_0^{R(x)} r \, dr \, d\theta \, dx \\ &= \int_0^H \int_0^{2\pi} \frac{1}{2} [R(x)]^2 \, d\theta \, dx \\ &= \int_0^H \left[ \frac{\theta}{2} [R(x)]^2 \right]_{\theta=0}^{2\pi} dx \\ &= \pi \int_0^H [R(x)]^2 dx \end{aligned}$$

b)

```
R(x)
  if x ≤ 3 then R = x
  else if 3 ≤ x ≤ 5 then R = 3
  else if 5 ≤ x ≤ 6 then R = 13 - 2x
  else if 6 ≤ x then R = 1
  Return R
```

c)

```
volume(R(x), H, n)
  x = 0
  V =  $\frac{1}{2}$  ([R(0)]2 + [R(H)]2)
  for i = 1, ..., n - 1
    x = x + Dx
    V = V + [R(x)]2
  end for
  V = V * 3.14
  Return V
```

- d) See the program **p61.c**.
- e) See the program **p61e.c**. This program uses Algorithm 6.2. from the book. This version is easier to modify for other applications.

### 6.7.2; A Class Hierarchy for Scalar ODE Solvers

```

a) class ODESolver_prm
    data:
        u0, f, Dt
        tstop
        method
        ...
    methods
        constructor()
        create()
        default()
        read()
        write()

b) class ODESolver
    data:
        prm
    methods:
        constructor(ODESolver_prm p)
            prm = p
        calculate()

c) class Heun, subclass of ODESolver
    data:
    methods:
        constructor(ODESolver_prm p)
            ODESolver.constructor.(p)
        calculate()
            u[0]=u0
            for i=1, ..., n
                v=f(u[i])
                u[i+1]=u[i]+dt (v*f(u[i] + dt*v ))/2
            end for
            return u

```

- d)-f)** For implementatons in Python see **ODE.py**. The Java and C++ classes are shown in their own sections. (The C++ classes use a slightly different scheme.)
- g)** We can test the programs using the problem from exercise 2.1;  $u'(t) = 1+4r(t)$ ,  $r(0) = 0$ . We know that the analytical solution is

$$r(t) = \frac{1}{4}(e^{4t} - 1)$$

which gives the results  $r(0.5) = 1.597$  and  $r(1) = 13.400$ . We compare this to the results we get by running **p62.py**:

```
>python p62.py -d 0.01 -s 1 -u 0 -f '1+4*u' -m RK
Dt=0.01 tstop=1 npoints=100 u0=0 f='1+4*u' method=RK
13.3995310153
```

```
>python p62.py -d 0.01 -s 0.5 -u 0 -f '1+4*u' -m Heun
Dt=0.01 tstop=0.5 npoints=50 u0=0 f='1+4*u' method=Heun
1.596308904
```

### 6.7.3; Software for Systems of ODEs

a)

*Heun's method for systems of ODEs,  
storing computed values in an array.*

```
heun(f, g, Y0, Z0, Δt, N)
  y0 = Y0
  z0 = Z0
  for n = 0, ..., N - 1
    v = f(yn, zn)
    w = g(yn, zn)
    yn+1 = yn +  $\frac{\Delta t}{2}$  [v + f(yn + Δtv, zn + Δtw)]
    zn+1 = zn +  $\frac{\Delta t}{2}$  [w + g(yn + Δtv, zn + Δtw)]
  end for
  return (y0, y1, ..., yN), (z0, z1, ..., zN)
```

*Heun's method for systems of ODEs,  
returning only the final values.*

```
heun(f, g, Y0, Z0, Δt, N)
  y0 = Y0
  z0 = Z0
  for n = 0, ..., N - 1
    v = f(y, z)
    w = g(y, z)
    y2 = y +  $\frac{\Delta t}{2}$  [v + f(y + Δtv, z + Δtw)]
    z2 = z +  $\frac{\Delta t}{2}$  [w + g(y + Δtv, z + Δtw)]
    y = y2
    z = z2
  end for
  return (y, z)
```

**b)+c)** For implementation in Python, see **ODEs.py**.

**d)** We can test this program using the problem from exercise **3.1**. Simply run **p63.py** a few times with different values for *tstop*, e.g..

```
>python p63.py -d 0.001 -s 2 -y 1.9 -z 0.1 -f '(2-v)*u' -g '(u-1)*v'
```

and compare the results with the arrays generated by **ex31.m**.

## Programs (C,C++, Python, Java )

### p61.c

```
/* A simple c program showing implementations of the
 * functions from project 6.1.
 */
#include <stdio.h>

double R(double x);
double volume(double H, int n, double (*Rfunk)(double x));

int main (int argc, char *argv[]) {
    double result;

    result = volume(8, 1000, R);
    printf("Volume: %lf\n", result);
}

double volume(double H, int n, double (*Rfunk)(double x)){
    double Dx, V, x;
    int i;
    Dx=H/n;
    x=0;
    printf("Dx: %lf\n", Dx);
    V=0.5*((*Rfunk)(0)*(*Rfunk)(0)+(*Rfunk)(H)*(*Rfunk)(H));
    for (i=1; i<n; i++){
        x=x+Dx;
        V=V+(*Rfunk)(x)*(*Rfunk)(x);
    }
    V=3.14159*Dx*V;
    return V;
}

double R(double x){
    double R;
    if (x <= 3) R=x;
    else if (x <= 5) R=3;
    else if (x <= 6) R=13-2*x;
    else R=1;
    return R;
}
```

### p61e.c

```
/* This program does the same as program p61.c,
 * but using Algorithm 6.2.
 */
#include <stdio.h>
```

```

double f(double x);
double trapezoidal(double a, double b, int n, double (*function)(double x));
double R(double x);

int main (int argc, char *argv[]) {
    double result;

    result = trapezoidal(0, 8, 100, f);
    printf("Volume: %lf\n", result);
}

double trapezoidal(double a, double b, int n, double (*function)(double x)){
    double h, s, x;
    int i;
    h=(b-a)/n;
    s=0;
    x=a;
    for (i=1; i<n; i++){
        x=x+h;
        s=s+(*function)(x);
    }
    s=s+0.5*((*function)(a)+(*function)(b));
    s=h*s;
    return s;
}

double R(double x){
    double R;
    if (x <= 3) R=x;
    else if (x <= 5) R=3;
    else if (x <= 6) R=13-2*x;
    else R=1;
    return R;
}

double f(double x){
    double res;
    res= 3.1415*R(x)*R(x);
    return res;
}

```

## ODE.py

```

import sys
from Numeric import *

class ODE:
    """
    Base class for numerical methods for ODEs.

```

```

"""

def __init__(self, p):
    self.prm = p # ODE_prm object

def calculate(self):
    """Perform integration."""
    # to be implemented in subclasses
    return "ODE.calculate; not impl. in subclass"

class Euler(ODE):
    """
    Euler's method.
    """
    def __init__(self, p):
        ODE.__init__(self, p)

    def calculate(self):
        p = self.prm; f = p.f; n = p.npoints; u0 = p.u0; Dt=p.dt;
        u = zeros(n+1, Float)
        u[0]=u0 #initial condition
        # advance n steps:
        for i in range (0,n,1):
            u[i+1] = u[i]+Dt*f(u[i])
        return u

class RK(ODE):
    """
    4. Order Runge-Kutta.
    """
    def __init__(self, p):
        ODE.__init__(self, p)

    def calculate(self):
        p = self.prm; f = p.f; n = p.npoints; u0 = p.u0; Dt=p.dt;
        u = zeros(n+1, Float)
        u[0]=u0 #initial condition
        # advance n steps:
        for i in range (0,n,1):
            F1 = f(u[i])
            F2 = f(u[i]+Dt*0.5*F1)
            F3 = f(u[i]+Dt*0.5*F2)
            F4 = f(u[i]+Dt*F3)
            u[i+1]=u[i] + Dt*(F1 + 2*F2 + 2*F3 +F4)/6
        return u

class Heun(ODE):
    """
    Heun's method, 2. order Runge-Kutta.
    """

```



```

def __init__(self, p):
    ODE.__init__(self, p)

def calculate(self):
    p = self.prm; f = p.f; n = p.npoints; u0 = p.u0; Dt=p.dt;
    u = zeros(n+1, Float)
    u[0]=u0 #initial condition
    # advance n steps:
    for i in range (0,n,1):
        v = f(u[i])
        u[i+1] = u[i]+0.5*Dt*(v+f(u[i] + Dt*v))
    return u

class ODE_prm:
    """
    Holds all parameters needet to initiate objects
    in the ODE hierarcy.
    """

    def __init__(self):
        self.default()
        return

    def default(self):
        """assign appropriate default values to all parameters"""
        self.tstop = 1
        self.u0 = 1
        self.dt = 0.01
        self.f = Function('1+x', independent_variable='x')
        self.method = "Heun"
        self.npoints = int(self.tstop/self.dt)
    def read(self, argv=sys.argv[1:]):
        # manual parsing
        for i in range(0,len(argv),2):
            if argv[i] == "-s": self.tstop = float(argv[i+1])
            if argv[i] == "-d": self.dt = float(argv[i+1])
            if argv[i] == "-f": self.f = Function(argv[i+1])
            if argv[i] == "-m": self.method = argv[i+1]
            if argv[i] == "-u": self.u0 = float(argv[i+1])
        self.npoints = int(self.tstop/self.dt)
    def write(self):
        print "Dt=%g tstop=%g npoints=%g u0=%g f='%s' method=%s" % \
            (self.dt, self.tstop, self.npoints, self.u0, \
            self.f.__name__, self.method)

    def create(self):
        """Create subclass of ODE"""
        code = "i = %s(self)" % self.method
        exec(code) # turn string into Python code

```

```

        return i

class Function:
    """
    Unified treatment of functions; strings or function objects.
    Examples on usage:

        def myfunc(u):
            return 1+x

        f = Function(myfunc, 'x') # attach Python function
        v = f(1.2)

        f = Function('1+t', 't') # specify function by string
        v = f(1.2)
    """
    def __init__(self, f, independent_variable='u'):
        self.f = f # expression or function object
        self.var = independent_variable # 'x', 't' etc.
        if type(f) == type(""):
            self.f_is_string = 1
            self.__name__ = self.f
        else:
            # function object:
            self.f_is_string = 0
            self.__name__ = self.f.__name__
    def __call__(self, u):
        if self.f_is_string:
            exec("%s = %g" % (self.var, u))
            return eval(self.f)
        else:
            return self.f(u)

```

### **p62.py**

```

#!/usr/bin/env python
from ODE import * # give access to library
from math import *
from sys import *

o=ODE_prm()
o.read(sys.argv[1:])
o.write()
i=o.create()
result = i.calculate()
print result[-1]

```

### **Java classes for Project 6.7.2**

```

class ODESolver {

```

```

public ODESolver_prm prm;

public ODESolver (ODESolver_prm p)
{ prm = p; }

public double [] calculate ()
{
System.out.println("ODE.calculate; not impl. in subclass");
    double k [] = new double[1];
return k;
}
}

class Heun extends ODESolver {
    public Heun (ODESolver_prm p)
    { super(p); }

    public double [] calculate ()
    {
        double dt = prm.dt; double u0 = prm.u0; int n = prm.n;
Func f = prm.f;
double u [] = new double[n+1];
        u[0] = u0; // initial condition

        // advance n steps:
        for (int i = 0; i < n; i++) {
            double v=f.f(u[i]);
            u[i+1] = u[i] + 0.5*dt*(v + f.f( u[i] + dt*v ));
        }
return u;
    }
}

class Euler extends ODESolver {
    public Euler (ODESolver_prm p)
    { super(p); }

    public double [] calculate ()
    {
        double dt = prm.dt; double u0 = prm.u0; int n = prm.n;
Func f = prm.f;
double u [] = new double[n+1];
        u[0] = u0; // initial condition

        // advance n steps:
        for (int i = 0; i < n; i++) {
            u[i+1] = u[i] + dt*f.f(u[i]);
        }
return u;
    }
}

```

```

class RK extends ODESolver {
    public RK (ODESolver_prm p)
    { super(p); }

    public double [] calculate ()
    {
        double dt = prm.dt; double u0 = prm.u0; int n = prm.n;
Func f = prm.f;
double u [] = new double[n+1];
        u[0] = u0; // initial condition

        // advance n steps:
        for (int i = 0; i < n; i++) {
            double F1 = f.f(u[i]);
            double F2 = f.f(u[i] + dt*0.5*F1);
            double F3 = f.f(u[i] + dt*0.5*F2);
            double F4 = f.f(u[i] + dt*F3);
            u[i+1] = u[i] + dt*(F1 + 2*F2 + 2*F2 + F4)/6;
        }
return u;
    }
}

class ODESolver_prm {
    public double u0, dt, tstop;
    public Func f;
    public int n;
    public String method;

    public ODESolver_prm ()
    { /* default values */
u0=1; dt=0.01; tstop=1; f = new f2();
method = "Heun";
        n= (int) (tstop/dt);
    }

    public void read (String argv[])
    {
int i;
for (i = 0; i < argv.length; i=i+2) {
    if (argv[i].compareTo("-s") == 0) {
tstop = Double.valueOf(argv[i+1]).doubleValue();
    }
    if (argv[i].compareTo("-d") == 0) {
dt = Double.valueOf(argv[i+1]).doubleValue();
    }
    if (argv[i].compareTo("-u") == 0) {
        u0 = Integer.valueOf(argv[i+1]).intValue();
    }
    if (argv[i].compareTo("-m") == 0) {
method = argv[i+1];
    }
}
}

```

```

    }
}
    n= (int) (tstop/dt);
}

public void write ()
{ System.out.println("Dt=" + dt + " tstop=" + tstop +
    " u0=" + u0 + " n=" + n +
" method=" + method);
}

public ODESolver create ()
{
ODESolver i;
if (method.compareTo("Heun") == 0) {
    i = new Heun(this);
}
else if (method.compareTo("Euler") == 0) {
    i = new Euler(this);
}
else if (method.compareTo("RK") == 0) {
    i = new RK(this);
} else {
    i = new Heun(this);
}
return i;
}
}

```

## C++ classes for Project 6.7.2

```

class ODESolver_prm
{
public:
    char          method[30]; // name of subclass in ODESolver hierarchy
    ODEProblem*  problem;    // pointer to user's problem class
    ODESolver*   create ();  // create correct subclass of ODESolver
};

ODESolver* ODESolver_prm::create ()
{
    ODESolver* ptr = NULL;
    if (strcmp(method, "ForwardEuler") == 0)
        ptr = new ForwardEuler (problem);
    else if (strcmp(method, "RungeKutta4") == 0)
        ptr = new RungeKutta4 (problem);
    else if (strcmp(method, "Heun4") == 0)
        ptr = new Heun4 (problem);
    else {

```

```

        cout << "\n\nODESolver_prm::create:\n\t"
             << "Method " << method << " is not available\n\n";
        exit(1);
    }
    return ptr;
}
class ODESolver
{
protected:          // members only visible in subclasses
    ODEProblem* eqdef; // definition of the ODE in user's class
public:             // members visible also outside the class
    ODESolver (ODEProblem* eqdef_)
        { eqdef = eqdef_; }
    virtual ~ODESolver () {} // always needed, does nothing here...
    virtual void init() {} // initialize solver data structures
    virtual void advance (MyArray<double>& y, double& t, double& dt);
};
class ODESolver
{
protected:          // members only visible in subclasses
    ODEProblem* eqdef; // definition of the ODE in user's class
public:             // members visible also outside the class
    ODESolver (ODEProblem* eqdef_)
        { eqdef = eqdef_; }
    virtual ~ODESolver () {} // always needed, does nothing here...
    virtual void init() {} // initialize solver data structures
    virtual void advance (MyArray<double>& y, double& t, double& dt);
};

#endif

void ODESolver::advance(MyArray<double>& /*y*/,
                       double& /*t*/, double& /*dt*/)
{
    cout << "\n\nODESolver::advance:\n\t"
         << "This function must be implemented in a subclass!\n\n";
}
class ForwardEuler : public ODESolver
{
    MyArray<double> scratch1; // needed in the algorithm
public:
    ForwardEuler (ODEProblem* eqdef_);
    virtual void init (); // for allocating scratch1
    virtual void advance (MyArray<double>& y, double& t, double& dt);
};
ForwardEuler::ForwardEuler(ODEProblem* eqdef_) : ODESolver(eqdef_) {}

void ForwardEuler::init ()
{

```

```

    // allocate internal data structure:
    scratch1.redim (eqdef->size());
}

void ForwardEuler::advance(MyArray<double>& y, double& t, double& dt)
{
    eqdef->equation (scratch1, y, t); // evaluate scratch1 (as f)
    const int n = y.size();
    for (int i = 1; i <= n; i++)
        y(i) += dt * scratch1(i);
    t += dt;
}

class RungeKutta4 : public ODESolver
{
    MyArray<double> scratch1, scratch2, scratch3; // needed in algorithm
public:
    RungeKutta4 (ODEProblem* eqdef_);
    virtual void init ();
    virtual void advance (MyArray<double>& y, double& t, double& dt);
};

RungeKutta4::RungeKutta4(ODEProblem* eqdef_) : ODESolver (eqdef_) {}

void RungeKutta4::init ()
{
    // allocate internal data structure:
    const int n = eqdef->size();
    scratch1.redim (n); scratch2.redim (n); scratch3.redim (n);
}

void RungeKutta4::advance (MyArray<double>& y, double& t, double& dt)
{
    const double dt2 = 0.5*dt;
    const double dt6 = dt/6.0;
    const int n = y.size();
    eqdef->equation (scratch1, y, t);
    int i;
    for (i = 1; i <= n; i++)
        scratch2(i) = y(i) + dt2 * scratch1(i);
    eqdef->equation (scratch1, scratch2, t+dt2);
    for (i = 1; i <= n; i++)
        scratch2(i) = y(i) + dt2 * scratch1(i);
    eqdef->equation (scratch3, scratch2, t+dt2);
    for (i = 1; i <= n; i++)
        {
            scratch2(i) = y(i) + dt * scratch3(i);
            scratch3(i) = scratch1(i) + scratch3(i);
        }
    eqdef->equation (scratch1, scratch2, t+dt);
    eqdef->equation (scratch2, y, t);
}

```

```

    for (i = 1; i <= n; i++)
        y(i) = y(i) + dt6*(scratch1(i) + scratch2(i) + 2*scratch3(i));
    t += dt;
}

class Heun : public ODESolver
{
    MyArray<double> scratch1, scratch2, scratch3; // needed in algorithm
public:
    Heun (ODEProblem* eqdef_);
    virtual void init ();
    virtual void advance (MyArray<double>& y, double& t, double& dt);
};
Heun::Heun(ODEProblem* eqdef_) : ODESolver (eqdef_) {}

void Heun:: init ()
{
    // allocate internal data structure:
    const int n = eqdef->size();
    scratch1.redim (n); scratch2.redim (n); scratch3.redim (n);
}

void Heun:: advance (MyArray<double>& y, double& t, double& dt)
{
    const double dt2 = 0.5*dt;
    const int n = y.size();
    eqdef->equation (scratch1, y, t);
    int i;
    for (i = 1; i <= n; i++)
        scratch2(i) = y(i) + dt *scratch1(i);
    eqdef->equation (scratch3, scratch2, t);
    for (i = 1; i <= n; i++)
        y(i) = y(i) + dt2*(scratch1(i) + scratch3(i));
    t += dt;
}

```

### **The MyArray template class, used in the C++ classes.**

```

template <class T>
class MyArray
{
protected:
    T*      A;                // vector entries (C-array)
    int     length;
    void    allocate (int n); // allocate memory, length=n
    void    deallocate();    // free memory
public:
    MyArray ();              // MyArray<T> v;
    MyArray (int n);        // MyArray<T> v(n);
}

```



```

MyArray (const MyArray<T>& w);           // MyArray<T> v(w);
~MyArray ();                             // clean up dynamic memory

int redim (int n);                         // v.redim(m);
int size () const { return length; }      // n = v.size();

void operator= (const MyArray<T>& w);     // v = w;
T operator() (int i) const;              // a = v(i);
T& operator() (int i);                   // v(i) = a;

void print (ostream& o) const;           // v.print(cout);
};
template<class T>
void MyArray<T>::allocate(int n)
{
    length = n;
    A = new T[n];
}

template<class T>
void MyArray<T>::deallocate()
{
    delete [] A;
    length = 0;
}

template<class T> MyArray<T>::MyArray()
{ A = NULL; length=0; }

template<class T> MyArray<T>::MyArray(int n)
{ allocate(n); }

template<class T> MyArray<T>::MyArray(const MyArray<T>& w)
{
    allocate(w.size());
    *this = w;
};

template<class T> MyArray<T>::~MyArray()
{ deallocate(); }

template<class T>
int MyArray<T>::redim(int n)
{
    if (length==n)
        return 0;
    if (A!= NULL)
        deallocate();
    allocate(n);
    return 1;
}

```

```

};

template<class T>
void MyArray<T>::operator=(const MyArray<T> & w)
{
    redim (w.size());
    for (int i=0; i<length; i++)
        A[i] = w.A[i];
}

template<class T>
inline T MyArray<T>::operator()(int i) const
{
#ifdef SAFETY_CHECKS
    if (i < 1 || i > length)
        cout << "MyArray::operator(), illegal index, i=" << i;
#endif
    return A[i-1];
}

template<class T>
inline T& MyArray<T>::operator()(int i)
{
#ifdef SAFETY_CHECKS
    if (i < 1 || i > length)
        cout << "MyArray::operator(), illegal index, i=" << i;
#endif
    return A[i-1];
}

template<class T>
inline ostream& operator<< (ostream& o, const MyArray<T>& v)
{ v.print(o); return o; }

template<class T>
void MyArray<T>::print(ostream& o) const
{
    for (int i=1; i<=length; i++)
        o << (*this)(i) << ((i==length) ? "" : " ");
}

```

### **A sample problem, for testing the C++ program.**

```

class Simprob : public ODEProblem
{
protected:
    double c1,c2,c3,c4,omega; // problem dependent paramters
public:
    Simprob () {}
}

```

```

    virtual void equation (MyArray<double>& f,
                          const MyArray<double>& y, double t);
    virtual int  size () { return 1; } // 2x2 system of ODEs
    virtual void scan ();
    virtual void print (ostream& os);
};

void Simprob::equation(MyArray<double>& f,
                      const MyArray<double>& y, double t)
{
    f(1) = c1+c2*y(1);
}

void Simprob:: scan ()
{
    // first we need to do everything that ODEProblem::scan does:
    ODEProblem::scan();
    // additional reading here:
    cout << "Give c1, c2: ";
    cin >> c1 >> c2;
    print(cout); // convenient check for the user
}

void Simprob:: print (ostream& os)
{
    // print everything that ODEProblem::print prints:
    ODEProblem::print(os);
    // print the equation:
    os << "The equation solved by class Simprob reads\n"
        << "dy/dt = " << c1 << " + " << c2<<"*y\n";
}

int main (int argc, const char* argv[])
{
    Simprob problem;
    problem.scan(); // read input data and initialize
    problem.timeLoop(); // solve problem
}

```

## ODEs.py

```

import sys
from Numeric import *

class ODEs:
    """
    Base class for numerical methods for ODEs.

```

```

"""

def __init__(self, p):
    self.prm = p # ODEs_prm object

def calculate(self):
    """Perform integration."""
    # to be implemented in subclasses
    return "ODEs.calculate; not impl. in subclass"

class Heun(ODEs):
    """
    Heun's method, 2. order Runge-Kutta.
    """
    def __init__(self, p):
        ODEs.__init__(self, p)

    def calculate(self):
        p = self.prm; f = p.f; g = p.g; n = p.npoints; y0 = p.y0; z0 = p.z0; Dt
        u = zeros(n+1, Float)
        y=y0 #initial conditions
        z=z0
        # advance n steps:
        for i in range (0,n,1):
            v = f(y,z)
            w = g(y,z)
            y2 = y +Dt*0.5*(v + f(y+Dt*v,z+Dt*w))
            z2 = z +Dt*0.5*(w + g(y+Dt*v,z+Dt*w))
            y=y2
            z=z2
        return (y,z)

class ODEs_prm:
    """
    Holds all parameters needet to initiate objects
    in the ODEs hierarchy.
    """
    def __init__(self):
        self.default()
        return

    def default(self):
        """assign appropriate default values to all parameters"""
        self.tstop = 1
        self.y0 = 1
        self.z0 = 1
        self.dt = 0.01

```

```

        self.f = Function('y+z', independent_variable='y', \
                           independent_variable2='z')
        self.g = Function('y-z', independent_variable='y', \
                           independent_variable2='z')
        self.method = "Heun"
        self.npoints = int(self.tstop/self.dt)
def read(self, argv=sys.argv[1:]):
    # manual parsing
    for i in range(0, len(argv), 2):
        if argv[i] == "-s": self.tstop = float(argv[i+1])
        if argv[i] == "-d": self.dt = float(argv[i+1])
        if argv[i] == "-f": self.f = Function(argv[i+1])
        if argv[i] == "-g": self.g = Function(argv[i+1])
        if argv[i] == "-m": self.method = argv[i+1]
        if argv[i] == "-y": self.y0 = float(argv[i+1])
        if argv[i] == "-z": self.z0 = float(argv[i+1])
    self.npoints = int(self.tstop/self.dt)
def write(self):
    print "Dt=%g tstop=%g npoints=%g y0=%g z0=%g f='%s' g='%s' \
          method=%s" % \
          (self.dt, self.tstop, self.npoints, self.y0, self.z0, \
           self.f.__name__, self.g.__name__, self.method)

def create(self):
    """Create subclass of ODE"""
    code = "i = %s(self)" % self.method
    exec(code) # turn string into Python code
    return i

class Function:
    """
    Unified treatment of functions; strings or function objects.
    Examples on usage:
        def myfunc(x,y):
            return x+y

        f = Function(myfunc, 'x','y') # attach Python function
        v = f(2,1)
        print v

        f = Function('1+x-2*y', 'x', 'y') # specify function by string
        v = f(1,2)
        print v
    """
def __init__(self, f, independent_variable='u', \
              independent_variable2='v'):
    self.f = f # expression or function object
    self.var = independent_variable # 'x', 't' etc.
    self.var2 = independent_variable2 # 'x', 't' etc.

```

```

    if type(f) == type(""):
        self.f_is_string = 1
        self.__name__ = self.f
    else:
        # function object:
        self.f_is_string = 0
        self.__name__ = self.f.__name__
def __call__(self, u, h):
    if self.f_is_string:
        exec("%s = %g" % (self.var, u))
        exec("%s = %g" % (self.var2, h))
        return eval(self.f)
    else:
        return self.f(u,h)

```

### **p63.py**

```

#!/usr/bin/env python
from ODEs import * # give access to library
from math import *
from sys import *

o=ODEs_prm()
o.read(sys.argv[1:])
o.write()
i=o.create()
result = i.calculate()
print result

```