



Multivariate density estimation using the local Gaussian correlation

Building Bridges at Bislett

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- ▶ Let X_1, \dots, X_n be (possibly multivariate) stochastic variables having density $f(x)$.
- ▶ For some parametric family $\Psi = \{\psi(x, \theta) : \theta \in \Theta\}$ we may conclude that
 - ▶ $f(x) \in \Psi \Rightarrow$ estimate f by $\hat{f}(x) = \psi(x, \hat{\theta})$, or
 - ▶ $f(x) \notin \Psi \Rightarrow$ obtain $\hat{f}(x)$ non-parametrically.



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One possible **bridge** between the parametric and non-parametric worlds is provided by Hjort & Jones (1996):

- ▶ Estimate $f(x)$ by fitting $\psi(x, \theta)$ *locally*, obtaining $\hat{\theta} = \hat{\theta}(x)$, and

$$\hat{f}(x) = \psi(x, \hat{\theta}(x)).$$

Local likelihood density estimation



The parameter is estimated for each x by maximizing the local likelihood function:

$$\hat{\theta}(x) = \arg \max_{\theta} n^{-1} \sum_{i=1}^n K_h(X_i - x) \log \psi(X_i, \theta) - \int K_h(x - y) \psi(y, \theta) dy,$$

where the smoothing parameter h is our location on the **bridge**:

- ▶ If $h \rightarrow 0$ (as $n \rightarrow \infty$), the estimator compares with classical non-parametric methods.
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Choosing a bandwidth in between can thus be regarded as a *trade-off* between the two classical mindset - this is a semi-parametric estimator.



Suppose that we wish to estimate the p -variate probability density function $f(\mathbf{x})$ based on n samples $\mathbf{X}_1, \dots, \mathbf{X}_n$.

The two traditional and straightforward methods both have serious problems in the multivariate case:

Parametric model: can we summarize the entire dependence structure between all p variables in just a few parameters?

Non-parametric kernel estimator: poor performance because of the *Curse of Dimensionality*.

A problem



It is not so easy to scale the local likelihood directly up to higher dimensions.

For example, consider a 3-dimensional local Gaussian fit. Instead of directly estimating

$$f(x_1, x_2, x_3),$$

we must rather estimate

$$\boldsymbol{\mu}(\mathbf{x}) = \begin{pmatrix} \mu_1(x_1, x_2, x_3) \\ \mu_2(x_1, x_2, x_3) \\ \mu_3(x_1, x_2, x_3) \end{pmatrix}, \quad \boldsymbol{\sigma}(\mathbf{x}) = \begin{pmatrix} \sigma_1(x_1, x_2, x_3) \\ \sigma_2(x_1, x_2, x_3) \\ \sigma_3(x_1, x_2, x_3) \end{pmatrix}$$

and

$$\mathbf{R}(\mathbf{x}) = \begin{pmatrix} 1 & \rho_{12}(x_1, x_2, x_3) & \rho_{13}(x_1, x_2, x_3) \\ \rho_{21}(x_1, x_2, x_3) & 1 & \rho_{23}(x_1, x_2, x_3) \\ \rho_{31}(x_1, x_2, x_3) & \rho_{32}(x_1, x_2, x_3) & 1 \end{pmatrix}$$



Clearly, we need a simplification!

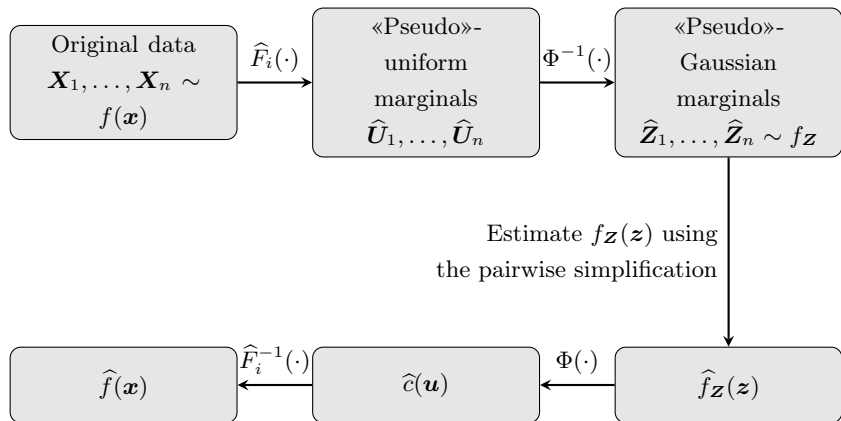
Assume that $f(x)$ has standard normal marginals.

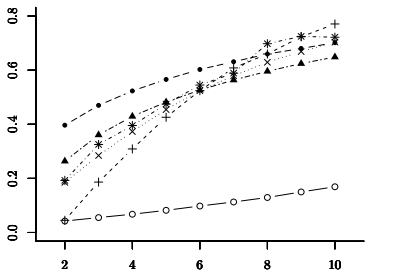
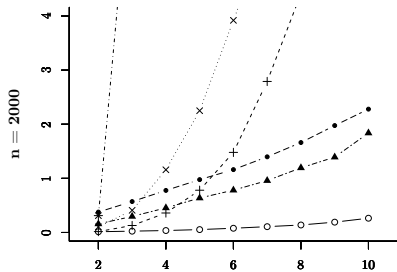
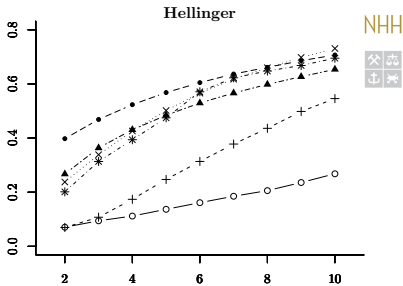
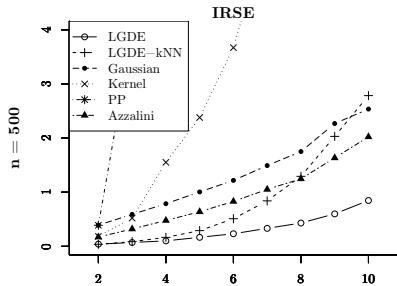
We can then fit the multivariate normal under the following restrictions:

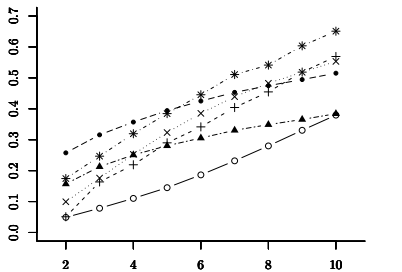
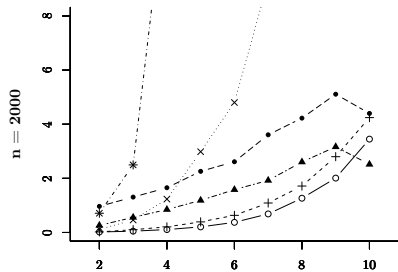
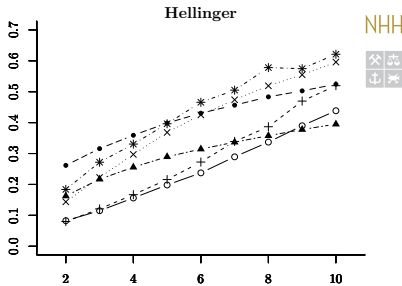
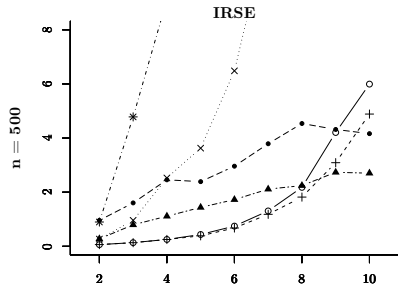
- ▶ Keep all local means and standard deviations fixed equal to 0 and 1 respectively.
- ▶ Estimate the local correlations *pairwise*:

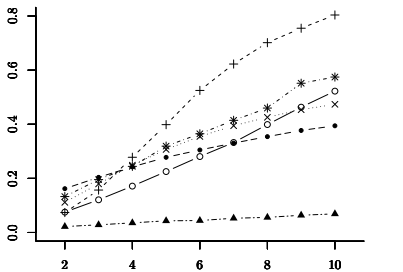
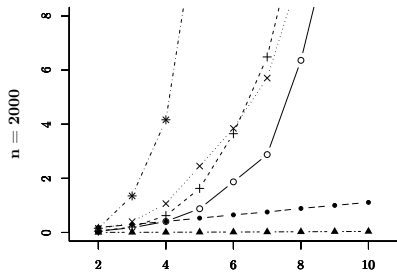
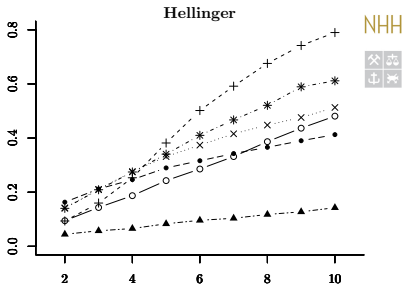
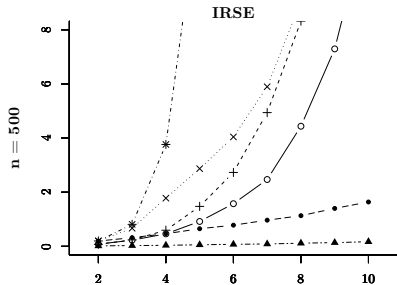
$$\hat{R}(z) = \begin{pmatrix} 1 & \hat{\rho}_{12}(z_1, z_2) & \cdots & \hat{\rho}_{1p}(z_1, z_p) \\ \hat{\rho}_{21}(z_1, z_2) & 1 & \cdots & \hat{\rho}_{2p}(z_2, z_p) \\ \vdots & \vdots & \ddots & \vdots \\ \hat{\rho}_{p1}(z_1, z_p) & \hat{\rho}_{p2}(z_2, z_p) & \cdots & 1 \end{pmatrix}$$

Algorithm for data that are not marginally st. normal









The conditional density



Let $\mathbf{X} = (\mathbf{X}_1, \mathbf{X}_2)$ be a stochastic vector with joint density $f(\mathbf{x}) = f(\mathbf{x}_1, \mathbf{x}_2)$. The conditional density of \mathbf{X}_1 given that $\mathbf{X}_2 = \mathbf{x}_2$ is

$$f_{\mathbf{X}_1|\mathbf{X}_2=\mathbf{x}_2}(\mathbf{x}_1|\mathbf{x}_2) = \frac{f(\mathbf{x}_1, \mathbf{x}_2)}{f(\mathbf{x}_2)}.$$



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Existing estimation methods can be roughly classified as (not a complete list!)

- ▶ **Kernel based:** Rosenblatt (1969), Bashtannyk & Hyndman (2001), Li & Racine (2007), Faugeras (2009).
- ▶ **Semi-parametric:** Hyndman et. al. (1996), Fan et. al. (1996), Hyndman & Yao (2002), Fan & Yim (2004).

Very few methods are implemented in available software, and even fewer allow both explanatory and response variables to be vectors.

The conditional density



Let $\mathbf{Z} = (\mathbf{Z}_1, \mathbf{Z}_2)$ be multivariate normally distributed with expectation vector and covariance matrix

$$\boldsymbol{\mu} = \begin{pmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{pmatrix}, \quad \boldsymbol{\Sigma} = \begin{pmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{pmatrix}.$$

Then $\mathbf{Z}_1 | \mathbf{Z}_2 = \mathbf{z}_2$ is multivariate normally distributed with

$$\begin{aligned} \boldsymbol{\mu}^* &= \boldsymbol{\mu}_1 + \boldsymbol{\Sigma}_{12} \boldsymbol{\Sigma}_{22}^{-1} (\mathbf{z}_2 - \boldsymbol{\mu}_2), \\ \boldsymbol{\Sigma}^* &= \boldsymbol{\Sigma}_{11} - \boldsymbol{\Sigma}_{12} \boldsymbol{\Sigma}_{22}^{-1} \boldsymbol{\Sigma}_{21}. \end{aligned}$$



Because of our pairwise fits, the same is true for our *locally* Gaussian fits:

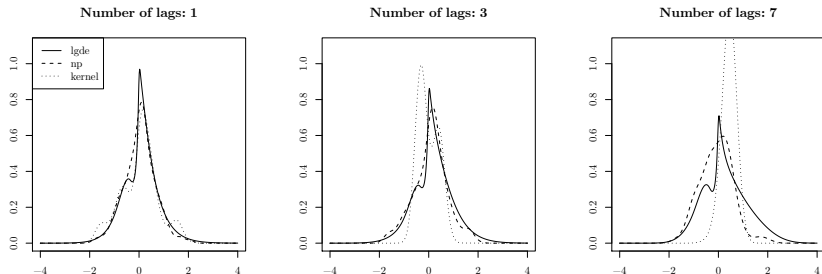
$$\frac{\psi(\mathbf{z}, \hat{R}(\mathbf{z}))}{\psi(\mathbf{z}_2, \hat{R}_{22}(\mathbf{z}_2))} = \psi(\mathbf{z}_1, \hat{\boldsymbol{\mu}}^*(\mathbf{z}), \hat{\boldsymbol{\Sigma}}^*(\mathbf{z})),$$

where

$$\begin{aligned}\hat{\boldsymbol{\mu}}^*(\mathbf{z}) &= \hat{\mathbf{R}}_{12}(\mathbf{z})\hat{\mathbf{R}}_{22}^{-1}(\mathbf{z})\mathbf{z}_2, \\ \hat{\boldsymbol{\Sigma}}^*(\mathbf{z}) &= \hat{\mathbf{R}}_{11}(\mathbf{z}) - \hat{\mathbf{R}}_{12}(\mathbf{z})\hat{\mathbf{R}}_{22}^{-1}(\mathbf{z})\hat{\mathbf{R}}_{21}(\mathbf{z}).\end{aligned}$$



- ▶ Observe 500 daily log-returns from the S&P500 index.
 - ▶ Estimate $f(x_t|x_{t-1})$, $f(x_t|x_{t-1}, x_{t-2}, x_{t-3})$ and $f(x_t|x_{t-1}, x_{t-2}, x_{t-3}, x_{t-4}, x_{t-5}, x_{t-6}, x_{t-7})$





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- ▶ With the LGDE, we use the same strategy for general stochastic variables using the **local** correlation.
- ▶ For **jointly Gaussian variables** we can easily estimate conditional densities using the formulas from an earlier slide.
- ▶ We simply replace the correlation coefficient with the **local** correlation in the same expressions, and obtain an estimator for general conditional densities that performs very well.



The same way of thinking has produced another useful result:

- ▶ **Jointly Gaussian variables** are independent *if and only if* the correlation between them is zero.
- ▶ In general, stochastic variables are independent *if and only if* the local Gaussian correlation is zero everywhere. (On the marginally standard normal scale)



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So there seems to be another **bridge** here:

- ▶ Using the LGC we can formulate statistical properties in terms of the Gaussian distribution.



Another property that is true for **jointly Gaussian variables**: X and Y are *conditionally independent* given Z if and only if the *partial* correlation between X and Y is zero.

- ▶ Our version: X and Y are *conditionally independent* given Z if and only if the local partial correlation is zero everywhere.
- ▶ This can, for example, be used to test for conditional independence.